TM AI COBOT



(All in ONE)





Techman Robot i is for reference o



What Is An Al Cobot?

Al Cobot is a collaborative robot that seamlessly blends three technological domains together - AI, Vision, and Cobot. This integration effectively combines the functions of a 'brain,' 'eyes,' and 'hands,' enabling the cobot to perform visual tasks, making judgments, and executing actions much like a human. Automating processes not only saves time and resources but also promotes effective human-robot collaboration, enhancing overall production quality, and adds a significant value to your factory. Fifteen years ago, collaborative robots introduced the concept of humans and robots working together. Today, the new generation of AI collaborative robots has turned the dream of having intelligent and reliable partners into a reality.



Industry Applications

TM AI Cobot offers exceptional performance and compatibility. Equipped with a built-in vision system, it enables the robot to perceive its surroundings. Its AI brain also translates image data into precise commands for tasks such as positioning and detection, seamlessly integrating with the robot arm to execute tasks efficiently. In the era of AI, **TM AI Cobot** is the best choice to for realizing smart factories.

Electronics Industry



CNC



Semiconductor Industry



Food Industry



Warehousing Industry



Machinery Industry



AI Cobot Application Scenario

The graphical interface of TM AI Cobot's integrated vision system eliminates the need for programming and enables a seamless process from image collection and annotation to training and deployment. It serves as an ideal solution for small and medium-sized enterprises (SMEs) lacking an AI or software division. Throughout production, AI Cobot accumulates valuable production history data, empowering companies to track, analyze, and integrate this

One-stop AI Solution





TM AI Cobot New Generation Al Cobot S Series



- **TM5S** Payload: 5 kg
- Reach: 946 mm



• Reach: 758 mm



Enhanced motor speed! 25% faster cycle time

- The joint speed of the 6th axis is increased from 225°/s to 450°/s
- Improved cycle time by 25%*, enchaning efficiency



Repeatability increased by up to 70% to 0.03 mm

Repeatability of TM5S/TM7S/TM12S/TM14S is 0.03mm, a 70%* improvement!



Control box is upgraded to IP54

- Control box has a IP54 rating and is suitable for harsh environment applications
- Effective protection against dust and water

TM14S

Payload: 14 kg

• Reach: 1100 mm



Brand new **Robot Stick** with Enabling Switch and **RESET** button

- pendant and TM Pen

Up to 31 safety functions certified by $T\ddot{U}V$ such as PL=d, Cat.3

- safety certification ISO 10218-1
- cost of safety control configuration

TMflow[™] 2 Series: Safe, Easy, and More Intelligent

- Innovative graphical UI with more exclusive software
- integration and robot application





TMflow



TM25**S**

- Payload: 25 kg
- Reach: 1902 mm

• Robot Stick with 3-position Enabling Switch, RESET button for safer operation • Combine with TM Screen for easy teaching, debugging, and control via teach

• TÜV-certified safety features in accordance with ISO 13849-1 and international

• Complies with SGS-certified UL & CSA in North America and CE in Europe

• Enables easy safety assessments with flexible safety functions that lower the

Include dozens of user-friendly function nodes to close the gap between

TM AI Cobot Al Collaborative Robot



TM5-700

- Payload: 6 kg
- Reach: 746 mm

TM5-900

Payload: 4 kg

• Reach: 946 mm

TM12

- Payload: 12 kg
- Reach: 1300 mm

TM14

Payload: 14 kg

• Reach: 1100 mm

TM5S/TM5-900

TM16

- Payload: 16 kg
- Reach: 917 mm

Industries Application



3D Bin Picking



Palletizing







AGV





Quality Inspection





Welding

TM7S/TM5-700

3D Bin Picking, Pick & Place, Assembly, Labeling, Quality Inspection, PCB Handling, Polishing & Deburring, Screwing

TM12S/ TM14S/ TM12/ TM14

3D Bin Picking, AGV, Pick & Place, Packaging, Palletizing, Conveyor Tracking, Machine Tending, PCB Handling, Polishing & Deburring, Screwing, Welding

TM25S/TM16/TM20

3D Bin Picking, AGV, Pick & Place, Packaging, Palletizing, Conveyor Tracking, Machine Tending, Polishing & Deburring, Injection Molding, Screwing, Welding

Polishing & Deburring Glue Dispensing

Injection Molding

Machine Tending

Screw Driving





Packaging

TM20

Payload: 20 kg

• Reach: 1300 mm

3D Bin Picking, AGV, Pick & Place, Assembly, Packaging, Labeling, Palletizing, Conveyor Tracking, Machine Tending, Quality Inspection, PCB Handling, Polishing & Deburring, Glue Dispensing, Screwing, Welding

TM Al Cobot Mobile & No Built-in Vision Robot Series

TM Mobile Series

TM5S-M / TM7S-M / TM12S-M / TM14S-M TM5M / TM12M / TM14M / TM16M / TM20M

TM Mobile Series cobots can be integrated with almost all AGV/AMR brands on the market. With its embedded vision and TM Landmark vision function, the mobile series is extremely suitable for applications and tasks that require mobility. Such as machine tending or palletizing.



No Built-in Vision Robot Series

TM5S-X/ TM7S-X/ TM12S-X/ TM14S-X TM5X/ TM12X/ TM14X/ TM16X/ TM20X

TM Robot Series offers robot arms with no built-in vision for users who want to integrate external cameras by themselves. Feel free to check on the pre-verified list of cameras from our TM Plug&Play[™] series to save time on finding a compatible camera.



Payload & Reach





More Freedom to Program the Cobot

TMflow[™] is a user-friendly software that allows you to create and edit robot tasks through a graphical interface using a series of function nodes, making it easy for first-time users to learn our flow-based programming without any robotics experience. If you prefer non-graphical programming, experience a more flexible way to program by

using the new Script Node and Script Project. The Script feature allows experienced engineers to program with complex logic, and freely edit robot tasks by compiling codes. Embrace the method that suits you best and enjoy coding with unparalleled freedom!

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Flow-based UI

Built-in vision



Script for Complex Logical Programming



Coordinate System with TM Landmark





TM Landmark

General robot has the coordinate system built on its base, when the relative position between the objects and the robot changes, the robot require re-adjustment. With TM Landmark, the coordinate system is built on the landmark, the robot will only need to scan the landmark and the coordinate info can be updated without re-adjustment. This is especially recommended to robot with AGV!

Visual Calibration

TM Calibration board can largely reduce the complexity of visual calibration process. Whether users are using EIH, ETH or Upwardlooking camera, just simply place the calibration board under the camera, press the button and TMvision[™] will do all the work!

Built-in vision application



TMcraft

Create Personalized Interface with TMcraft for 2nd Development

TMcraft is a new architecture that allows you to create your own customized UI or background program and embed it onto TMflow[™], our cobot programming software. It offers the freedom to develop third-party plug-and-play applications using **C#** and **WPF** development. Additionally, a wizard is available to facilitate the development of high-level applications, such as welding, palletizing, and sanding, making it easier to customize and create the applications you need.



 Developers can develop nodes in their own environment



■ Embed into TMflowTM using third-party plugins



TMvision™

A perfect integration of cobot and machine vision

- Hand and eye integration for time/labor-saving solution
- Powerful vision function: The combination of traditional machine vision and AI vision offers the user a comprehensive vision function including vision positioning, measurement, defect inspection, OCR and barcode reading
- Easily manage both robot arm and vision functions within a single software, eliminating the need to learn two separate programs and concerns about system compatibility or interface issues



• TM built-in vision, integrated in one system



 Integrating separate systems for robot arm and external vision

	TM built-in vision	Robot arm + External vision
Camera	All-in-one	Requires additional mechanism for integration
Camera signal cable and power cord	Internally routed cables	Externally routed cables can lead to problems like tangled or pulled cables or dust resulted from friction
Vision recognition system	5M color camera, auto focus, built-in light source, various applications	Complicated configuration of lens, camera, light source and software
Vision and Robot Programming	Integrated in one software TMflow™ for easy programming	Need to handle the communication interface of 2 different software
Charge	The cost of the robot arm includes the vision system	Additional charge of vision software /hardware is required

TM 3DVision[™]

A plug-and-play 3D vision solution requires no additional software/hardware integration

When incoming materials are stacked or arranged in different configurations, the positioning function may become ineffective or less accurate due to the limitations of a standard robot's 2D vision, which cannot capture 3D coordinates. To overcome this challenge, Techman Robot has introduced TM 3DVision[™], a 3D machine vision solution with paried designated Plug&Play 3D camera, designed to expand the range of items recognizable by the vision system and enhance the precision of both vision-based positioning and arm movement.



Traditional Solution

Requires more time and labor costs to integrate robot arm, 3D camera, and software from different brands

Features

- The integration of 3D software and TMflow™ interface achieves high integration and easy operation
- No additional vision controller is required. No need for complicated system handshaking settings
- Can be used with the collision check function and prevent any potential collision risks.
 This is highly recommended for the Random Bin Picking applications.



Picking up scattered materials



Significantly reduces integration costs and efforts, maintenance and accountability issues

rface achieves high integration and easy operation red for complicated system handshaking settings d prevent any potential collision risks.







Completely integrate hands, eyes and brain in automation field

TM AI+[™] Training Server is a software tool that will help you manage image data, set up AI training parameters, and train AI models. The AI solution can help you train a model that fits your needs effortlessly. This AI model can be applied to both the robot arm and machine vision, thus forming a powerful combination of the arm(cobot), eye(machine vision), and brain(AI). Easy and simple UI helps the user to rapidly and conveniently introduce AI vision technology to production. AI incorporating vision system can effectively eliminate quality issues resulted from fatigue or human error.

Features

- A graphical interface that is easy to learn
- Designed as a browser-based software that you can log in anywhere with a web browser
- All image data used for AI model training is stored in a local database to ensure enterprise classified data is secure
- Powerful AI Vision technology with capabilities including anomaly detection, classification, object detection, and semantic segmentation

Annotation

4 steps for easy AI model training



Image collection





Collect Image Data

 Take multiple photos of the object and upload them to TM AI+[™] Training Server

Training

Deployment

TM AI+™ Training Server

- Select the type of vision task: Classification, Detection, Segmentation, Anomaly Detection
- Label the uploaded image samples
- Configure training parameters and begin training
- Evaluate the training outcome

Import AI model

- Download the trained AI model from the training server to TM Robot or external camera
- Begin Al inference

Build quality traceability for your product

After an enterprise sells their product to customers, they will often need to deal with customers' feedback or complaints. Therefore, a comprehensive quality tracking system is essential for businesses to establish.

TM Image Manager is a software tool that is highly compatible with TM Robot's vision function. It can help you effectively manage the quality inspection records of each product. The inspector can monitor the inspection progress in real-time, and the results will automatically be recorded as image data. These data can be reviewed anytime in order to increase inspection accuracy. Furthermore, a quality resume can also be built for each product and the potential costs needed for after-sales service activities can be reduced.

Features

- Browser-based interface for intuitive and easy operation
- Manage inspection images and results through the database to address the needs of backup and search
- The user can filter the images of quality inspection by different conditions, like time, work order, barcode, etc. at any time
- Help inspectors to compare the images of inspection and standard item to effectively reduce the probability of misjudgement
- The user can plan and design inspection configuration to perform real-time monitoring on inspection position, result and progress



 Configuration inspection and progress review







The smart function software that helps you to deploy TMvision[™] to all required spots in the factory

TMvision[™], one of the most iconic functions of TM Robot, is now becoming more flexible to deploy. If you have requirements for setting up pure visual working areas in the factory or require multiple cameras in a single visual working area,

TM AI+[™] AOI Edge will be the best solution for you to optimize your implementation costs while fulfilling visual function needs.

Features

- Easy integration of TM AI+TM to improve the precision and width of AOI inspection
- Support TM Plug&PlayTM camera to save the time of camera integration
- User-friendly TMflow[™] interface is easy to master. No need for experienced workers to learn new software



■ TM AI+TM AOI Edge is compatible with both personal and industrial computers used in production lines. By connecting an external camera to a computer, users can utilize TMvision[™] to perform tasks such as defect inspection and measurement.

TMstudio Pro is offline programming simulation software for TM AI Cobot, enabling users to create multi-robot simulation scenes without the need for a physical robot.





2.Program

3.Simulate

Product Features



Validation

Detects collisions, ensures the robot's reach, and validates the workspace during programming, thereby minimizing errors during runtime.

Time Saving

Design your robot usage efficiently without setting up robot workstations in the real world

Reliable Planning

Program your robot system with accurate cycle time

Increase Revenue





1.Create a Scene

 Import CAD file instead of setting up in the real world Generate a path for the robot from CAD • Simulate multi-robot in the same virtual scene

 Program the same way as using TMflow[™] Import or export between TMstudio Pro and robot Test your project and TMcraft Node in the virtual scene

 Visualize the robot's reach in a virtual scene Check for collision detection and correct your solution • Estimate the robot's cycle time

Facilitate users in planning, simulating, and presenting solutions to end-customers, enabling clearer demonstrations and discussions in details to enhance sales success

TM Plug&PlayTM Solution

All leading robot peripherals work with Techman Robot and developed TM Plug&Play™ together, a suite integrating related software and hardware. All software and hardware are tested and verified to allow the user to download the software package and apply to the hardware they purchase. This can significantly reduce the time and labor costs required by producing hardware and programming for automation.

Start to use within 5 minutes



Simple, efficient, and fast production line introduction



TM certified, perfect integration, and usable upon installation

TM Robot works with peripheral equipment vendors to co-build a comprehensive TM Plug&Play™ eco system. Each certified TM Plug&Play[™] product has been calibrated and tested by TM Robot and peripheral equipment vendors. This ensures that users receive the optimal user experience and the most reliable robot operating quality.





Advantech AIR-3002022 -TM AI+ Training Server

ASPINA ARH350A Kit for TM





FlexiBowl® Kit for TM

ARS Autom

EWELLIX LIFTKIT-TM

Plug&Play for TM

COBOTRACKS Linear Motion



DH-Robotics Adaptive

Gripper DH-3 TM Kit



HIWIN Electric Gripper X-series

IDS Ensenso N36/N46 3D camera







NABELL Robot Flex

RoboDK Simulation and Offline

Programming Software for TM

NITTOSEIKO Pick and Drive System PD400TM

OnRobot Sander





Robotiq FTS-300-TM-KIT

Robotiq Adaptive Gripper 2-Finger 85/140 TM Kit







SMC Magnet Gripper Unit for Collaborative Robots

ΤΟΥΟ CHY2B-S80

GRIPKIT-CR-PRO-I

TMPlug&Play[▶] CERTIFIED



ATI 9105-TM-Axia80



FerRobotics ACF-K Active Contact Flange-Kit



Igus®KILEWS3D e-chain TM Kit - PMA TubesScrew Driver Solution



OnRobot 2FG7



Schmalz FXCB



HRC-03 TM-Kit



Basler Industrial Camera



Flir Industrial Camera

Mindman All-in-One Gripper

for TM Robot (3-Finger)



CKD RCKL/RHLF/RLSH -TM Gripper



Gimatic KIT-TM-J



Murrplastik Murrplastik FHS-SH-Set



Pickit Pickit3D Vision Solution



gripping EGP-C



More Information on



-**B**a

SCHUNK Changing by SCHUNK SCHUNK Collaborative - Plug & Work Portfolio gripping EGP-C han Robot



Universal Mobile Stand

TM AI Cobot S Series Specification

Specification									
м	lodel	TM5S	TM7S	TM5S-M	TM7S-M	TM5S-X	TM7S-X		
W	eight	23.9 kg	22.9 kg	23.9 kg	22.9 kg	23.6 kg	22.6 kg		
Maximum Payload		5kg	7kg	5kg	7kg	5kg	7kg		
R	each	946mm	758mm	946mm	758mm	946mm	758mm		
loint ranges	J1, J2, J4, J5, J6			+/- 360°					
Joint langes	J3	+/- 158°	+/- 152°	+/- 158°	+/- 152°	+/- 158°	+/- 152°		
	J1, J2, J3			210°/s					
Speed	J4, J5								
	J6			450°/s					
Max	. Speed			4.5m/s					
Repe	atability			+/- 0.03 #	IM				
Degree (Of Freedom			6 rotating jo	pints				
	Control hov			Digital In: 16 / Dig	ital Out: 16				
1/0	CONTIOUDOX			Analog In: 2 / Ana	log Out: 2				
1/0	TeelConn			Digital In: 3 / Dig	ital Out: 3				
	Tool Conn.	DO_0 (DO-0/AI) / DO_1 (DO-1/RS485-) / DO_2 (DO-2/RS485+)							
I/O Power Supply		24V 2.0A for control box; 24V 1.5A for tool							
IP Classification		IP54 (Robot Arm);	IP54 (Control Box)	IP54 (Ro	bot Arm)	IP54 (Robot Arm);	IP54 (Control Box		
Typical Power Consumption		240 watts							
Temperature		0~50°C							
Clea	nliness	ISO Class 3							
Powe	r Supply	100~240 VA	100~240 VA	\C, 50∼60 Hz					
I/O Ir	nterface	3×COM、1×HDMI、3×LAN、4×USB2.0、2×USB3.0							
Comm	unication	RS-232/RS-422/RS-485, Ethernet, Modbus TCP/RTU (master & slave)							
Comm	unication	PROFINET (optional), EtherNet/IP (optional)							
Programmin	ng Environment	TMflow (flowchart/script based)							
Certi	fication	CE, SEMI S2 (optional)							
AI & Robot Vision									
AI Function		Classification, O							
Application									
Application		Def							
Positioning Accuracy									
Eye in Ha	ind (Built in)	Auto-focused colo	N	/A					
Eye to Har	nd (Optional)	Support Maximum							
* ⁽¹⁾ The data in th	is table are measure	d by TM laboratory and	the working distance is	100mm. It should be no	ted that in practical				
applications, the	relevant values may	be different due to fact	ors such as the on-site a	ambient light source, of	ject characteristics,				
and vision progra	amming methods tha	at will affect the change	in accuracy.						
* ⁽²⁾ Refer to the of	⁽²⁾ Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.								

	Specification									
P	Model	TM12S	TM14S	TM25S	TM12S-M	TM14S-M	TM25S-M	TM12S-X	TM14S-X	TM25S-X
V	Veight	33.3 kg	33 kg	80.6Kg	33.3 kg	33 kg	80.6 Kg	33 kg	32.7 kg	80.3 Kg
Maxim	Maximum Payload		14kg	25kg	12kg	14kg	25kg	12kg	14kg	25kg
F	Reach	1300mm	1100mm	1902mm	1300mm	1100mm	1902mm	1300mm	1100mm	1902mm
loint ranges	J1, J2, J4, J5, J6					+/- 360°				
Jointranges	J3	+/- 162°	+/- 159°	+/- 166°	+/- 162°	+/- 159°	+/-166°	+/-162°	+/- 159°	+/- 166°
	J1, J2	130)°/s	100°/s	130	0°/s	100°/s	130)°/s	100°/s
	J3	210)°/s	130°/s	210	0°/s	130°/s	210)°/s	130°/s
Speed	J4	225	5°/s	195°/s	22	5°/s	195°/s	225	5°/s	195°/s
	J5	225	5°/s	210°/s	22	5°/s	210°/s	225	5°/s	210°/s
	J6	450)°/s	225°/s	450	0°/s	225°/s	450)°/s	225°/s
Max	x. Speed	4.5	5m/s	5.2m/s	4.	5m/s	5.2m/s	4.5	ōm/s	5.2m/s
Repo	eatability	+/- 0.	.03 mm	+/- 0.05 mm	+/- 0.	.03 mm	+/-0.05 mm	+/- 0.	03 mm	+/- 0.05 mm
Degree	Of Freedom				6	rotating joir	its			
	Control boy				Digital I	n: 16 / Digita	l Out: 16			
1/0	Control box				Analog	In: 2 / Analo	g Out: 2			
1/0	Tool Conn	Digital In: 3 / Digital Out: 3								
	Tool Conn.		DO_0 (DO-0/AI) / DO_1 (DO-1/RS485-) / DO_2 (DO-2/RS485+)							
I/O Po	wer Supply	24V 2.0A for control box; 24V 1.5A for tool								
IP Cla	IP Classification		IP54 (Robot Arm); IP54 (Control Box) IP54 (Robot Arm)						bot Arm); I	P54 (Control Box)
Typical Pow	Typical Power Consumption		0W	600W	40	0W	600W	40	0W	600W
Tem	perature	0~50°C								
Cle	anliness	ISO Class 3								
Pow	er Supply	100~240 VA	/C, 50~60 Hz	200~240 VAC, 50~60 Hz	24~6	i0 vdc	48~60 VDC	100~240 vA	кс, 50~60 Hz	200~240 VAC, 50~60 Hz
I/O I	Interface	2×COM、1×HDMI、3×LAN、2×USB2.0、4×USB3.0								
Comp	nunication	RS-232/RS-422/RS-485 Ethernet Modbus TCP/RTU(master & slave)								
comm	numeation	PROFINET (optional), EtherNet/IP (optional)								
Programmi	ng Environment	TMflow (flowchart/script based)								
Cert	Certification		CE, SEMI S2 (optional)							
		AI & Robot Vision								
AI F	AI Function		Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR							
Apr	Application		Positioning, 1D/2D Barcode Reading, OCR,							
~PF	Application		Defect Detection, Measurement, Assembly Check							
Position	ing Accuracy	2D Positioning: 0.1 mm* (1)								
Eye in H	and (Built in)	Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞						N/2	Ą	
Eye to Ha	and (Optional)	Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera* (2)								
* ⁽¹⁾ The data in thi	is table are measured	by TM laborat	tory and the	working distance is 10	0mm. It shou	uld be noted	that in			
practical applica	tions, the relevant valu	ues may be di	ifferent due 1	to factors such as the o	on-site ambie	ent light sour	ce, object			
characteristics, a	nd vision programmin	ng methods th	nat will affect	t the change in accura	cy.					
* ⁽²⁾ Refer to the of	ficial website of TM Pl	ug&Play for c	amera mode	Is compatible to TM R	obot.					



TM AI Cobot Specification

Model TM5-700 TM5-900 TM5M-700 TM5M-900 TM5X-700 TM5X-900 Weight 22.1kg 22.6kg 22.1kg 22.6kg 21.8kg 22.3kg Maximum Payload 6kg 4kg 6kg 4kg 6kg 4kg Reach 746mm 946mm 746mm 946mm 946mm				Spec	ification						
Weight 22.1kg 22.6kg 22.1kg 22.6kg 21.8kg 22.3kg Maximum Payload 6kg 4kg 6kg 4kg 6kg 4kg Reach 746mm 946mm 746mm 946mm 946mm 946mm	Mod	el	TM5-700	TM5-900	TM5M-700	TM5M-900	TM5X-700	TM5X-900			
Maximum Payload 6kg 4kg 6kg 4kg 6kg 4kg Reach 746mm 946mm 746mm 946mm 946mm 946mm	Weig	ht	22.1kg	22.6kg	22.1kg	22.6kg	21.8kg	22.3kg			
Reach 746mm 946mm 746mm 946mm 746mm 946mm 946mm	Maximum	Payload	6kg	4kg	6kg	4kg	6kg	4kg			
	Read	ch	746mm	946mm	746mm	946mm	746mm	946mm			
J1,J6 +/- 270° +/- 270° +/- 270° +/- 270° +/- 360° +/- 360°		J1,J6	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°			
Joint ranges J2, J4, J5 +/- 180° +/- 180° +/- 180° +/- 180° +/- 360° +/- 360°	Joint ranges	J2,J4,J5	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 360°	+/- 360°			
J3 +/- 155°		J3		+/- 155°							
J1,J2 180°/s		J1,J2	180°/s								
J3 225°/s		J3			22	5°/s					
Speed J4 225°/s	Speed	J4			22	5°/s					
J5 225°/s		J5			22	5°/s					
J6 225°/s		J6			225	5°/s					
Max. Speed 4 m/s	Max. Sp	peed			4 r	n/s					
Repeatability +/- 0.05 mm	Repeata	ability			+/- 0.0)5 mm					
Degree Of Freedom 6 rotating joints	Degree Of F	Freedom			6 rotati	ng joints					
Digital In: 16 / Digital Out: 16		Control box	Digital In: 16 / Digital Out: 16								
Analog In: 2 / Analog Out: 1	1/0		Analog In: 2 / Analog Out: 1								
Tool Conn. Digital In: 4 / Digital Out: 4	., -	Tool Conn.	Digital In: 4 / Digital Out: 4								
Analog In: 1 / Analog Out: 0		100100111		Analog In: 1 / Analog Out: 0							
I/O Power Supply 24V 2.0A for control box; 24V 1.5A for tool	I/O Power	I/O Power Supply		24V 2.0A for control box; 24V 1.5A for tool							
IP Classification IP54 (Robot Arm); IP32 (Control Box)	IP Classifi	IP Classification		IP54 (Robot Arm); IP32 (Control Box)							
Typical Power Consumption 220 watts	Typical Power C	Typical Power Consumption		220 watts							
Temperature 0-50°C	Temper	ature	0-50°C								
Cleanliness ISO Class 3	Cleanli	ness									
Power Supply 100-240 VAC, 50-60 Hz 22-60 VDC 100-240 VAC, 50-60 Hz	Power S	upply	100-240 VA	AC, 50-60 Hz	100-240 VA	AC, 50-60 Hz					
I/O Interface 3×COM \ 1×HDMI \ 3×LAN \ 4×USB2.0 \ 2×USB3.0	I/O Inte	rface	3×COM×1×HDMI×3×LAN×4×USB2.0×2×USB3.0								
Communication RS-232, Ethernet, Modbus TCP/RTU (master & slave)	Commun	ication	KS-232, Ethernet, Moddus TCP/RTU (master & slave)								
PROFINET (optional), EtherNet/IP (optional)			PROFINE I (optional), EtherNet/IP (optional)								
Programming Environment I Mflow (flowchart/script based)	Programming	Programming Environment		I MILOW (NOWCHART/SCRIPT Dased)							
CE, SEMI 52 (optional)	Certifica	ation		h a thtal a u	CE, SEMI S.	2 (optional)					
Al & Robot Vision	ALEuro	tion	AI & RO	bot vision	montation Anomaly B	stastics ALOCR					
Ai Function Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR	AIFUNC	AI Function		Depict Detection, Seg							
Application Defect Detection Measurement Assembly Check	Application			Positioning, 1D/2D E							
Derect Detection, Measurement, Assembly Check	Desible size Assures		De	Prect Detection, Measu							
Positioning Accuracy 2D Positioning: 0.1 mm ⁻¹⁴⁷	Positioning	Accuracy (Ruiltin)	Auto focused cel	2D Positioni		1/A					
Eve to Hand (Optional) Support Maximum 2X CidE 2D compresent 1X CidE 2D Compres + 1X 2D Compres ¹²	Eye in Hand	(Ontional)	Auto-locused col	Or camera with SM res		4/A					
* ^[1] The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in	* ^[1] The data in this ta	he are measured b	Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera * **								
practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object	practical application	the relevant value	es may be different du	ie to factors such as t	he on-site ambient lief	at source object					
characteristics, and vision programming methods that will affect the change in accuracy	characteristics and u	ision programming	methods that will aff	ect the change in acc	uracy	is source, object					
* ^[2] Refer to the official website of TM Plug& Play for camera models compatible to TM Robot	* ^[2] Refer to the officia	website of TM Plu	ug&Play for camera m	odels compatible to T	M Robot						

					Specif	
TM12	TM14	TM16	TM20	TM12M	TM14M	
32.8kg	32.5kg	32kg	32.8kg	32.8kg	32.5kg	
12kg	14kg	16kg	20kg	12kg	14kg	
L300mm	1100mm	917mm	1300mm	1300mm	1100mm	
+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	
+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	
+/-166°	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163°	
120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	
180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	
180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	
180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	
180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	
					4 r	
					+/- 0.	
					6 rotati	
				[Digital In: 16 /	
					Analog In: 2 /	
					Digital In: 4 /	
Analog In: 1 /						
				24V 2.0	A for control	
				IP54	(Robot Arm);	
					300 \	
					0-5	
					ISO C	
	100-240 VA	C, 50-60 Hz			22-60 VDC	
				3×COM、1×	HDMI \ 3×LA	
				RS-232, Ethe	rnet, Modbus	
				PROFINE	T (optional),	
				ΤN	Iflow (flowch	
					CE, SEMI S	
			AI & Rob	ot Vision	, ,	
	Classificati	on, Obiect De	etection, Segn	nentation. An	omaly Detect	
		Position	ning, 1D/2D Ba	arcode Readir	ng, OCR,	
		Defect Det	ection. Measu	rement. Asse	mbly Check	
			2D Positionin	g: 0.1 mm* ⁽¹⁾	,	
Auto-focused color camera with 5M resolution. Working distance						
S	upport Maxin	num 2 X GigF	2D cameras o	r 1X GigE 2D	Camera + 1>	
The data ir	this table are	measured by	TM laboratory	and the workin	g distance is 1	
at in practic	al application	s, the relevant	values may be	different due t	o factors such	
provine						
urce, object characteristics, and vision programming methods that will affect the ch						



Software Specification

TM AI+ Training Server Installation Requirements

Software Requirement	s					
TM AI+ Training Server Soft	ware version Ver. 2.14					
Hardware Requiremen	ts					
Operating System	Ubuntu 20.04 LTS Desktop *(1) (64-bit)					
CPU	7th Generation Intel [®] Core™ i7 Processors or above					
RAM	32 GB or above					
	Only support NVIDIA Turing and Ampere micro-architectures GPU*(2)*(3).					
Current in Courts	Recommendation: NVIDIA GeForce RTX 30 series (3060 12GB or above)					
Graphics Cards	NVIDIA RTX professional GPUs (A4000 16GB or above)					
	NVIDIA Quadro RTX professional GPUs (4000 or above)					
Storage	2TB or above (SSD Recommended)					
Communication Interface	Ethernet					
Language Support	EN, TW, CN, DE, ES, FR, JP, KO, PT, TH, VI					
* ⁽¹⁾ Linux on VM is not comp	* ⁽¹⁾ Linux on VM is not compatible.					
* ⁽²⁾ Not support GPU other	than NVIDIA, such as AMD and Intel.					
* ⁽³⁾ Not support with NVIDIA	A GPU of other micro-architectures,					
such as the GeForce RTX	such as the GeForce RTX 40 series based on the Ada Lovelace micro-architecture.					

TM Image Manager Installation Requirements

Software Requirement	s
TMflow Software Version	Ver. 2.14
Hardware Requiremen	ts
Operating System	Ubuntu 20.04
CPU	Intel i7 or above
RAM	16GB or above
Storage	SSD 2TB or above
Communication Interface	Ethernet
Language Support	EN, TW, CN
	1. Exclusive compatibility with TM AI Cobot and TM AI+ AOI Edge
Limitations	2. License fees are determined based on the number of connected devices,
LIIIIIduoiis	with a maximum of 10 devices ^{* (1)}
	3. Supports simultaneous image transmission for up to 10 devices* (2)
* ⁽¹⁾ When users purchase 10	devices, the system will no longer impose a maximum limit on the number of device connections.
* ⁽²⁾ Techman Robot can gua	rantee normal operation for up to 10 connected devices. Exceeding this limit may require users
to assess potential syste	m overload issues, such as reduced system performance.

TMstudio Pro System Requirements

Hardware Requiremen	Hardware Requirements					
Operating System Windows 10 or above						
CPU	Intel I7 Gen 7+, AMD Ryzen+					
Cores	4					
RAM	16GB RAM					
Storage	C Drive 30GB of available SSD storage					
Display Resolution	1920×1080 or above					

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